## Centro de Investigação em Matemática e Aplicações Departamento de Matemática Programa de Doutoramento em Matemática

## Seminário (online)

11 de maio de 2022, 15h

## A brief survey of the vector case of the Calculus of Variations

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Consider the typical variational problem

Minimize in  $u \in A$ :  $I(u) = \int_{\Omega} \varphi(\nabla u(x)) dx$ 

where feasible fields  $u \in A$  comply with boundary conditions (for instance)

 $u: \Omega \subset \mathbb{R}^N \to \mathbb{R}^m$ .

A is a certain subset of typical Sobolev spaces, and the integrand

 $\varphi: \mathbb{R}^{m \times N} \to \mathbb{R}$ 

is assumed to be continuous. These vector variational problems are fundamental in applications to models in non-linear elasticity of solids. It is well-known that a fundamental property to show existence of states of minimum energy is the so-called weak lower semicontinuity of the energy functional I, and this in turn is equivalent to the quasiconvexity property of the integrand  $\varphi$ . This property for  $\varphi$  is extremely difficult to check in specific examples (if not impossible) so that other important convexity properties were sought. These are polyconvexity (sufficient condition for quasiconvexity), and rankone convexity (necessary condition for quasiconvexity).

After a general survey, we report our own work about the analysis of the situation concerning the equivalence of quasiconvexity and rank-one convexity of integrands  $\varphi$ , for the case m = 2 (N > 1), which is an open problem.







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